

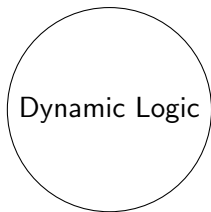
Dynamic Logic

How loops are actually recursion
Hype for Types

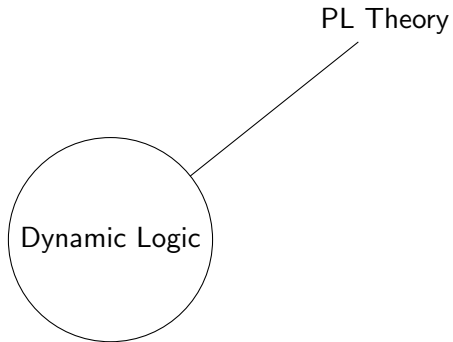
Jacob Neumann

08 October 2019

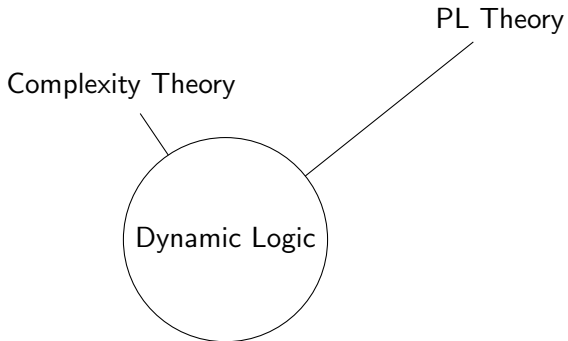
Dynamic Logic is everywhere



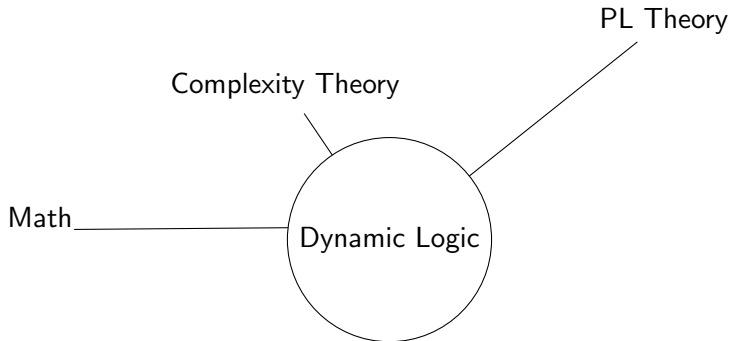
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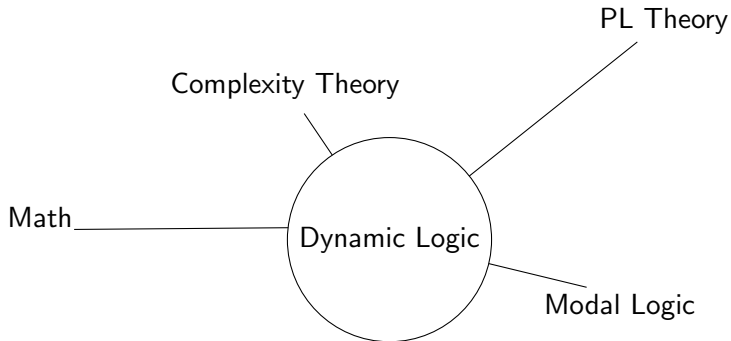
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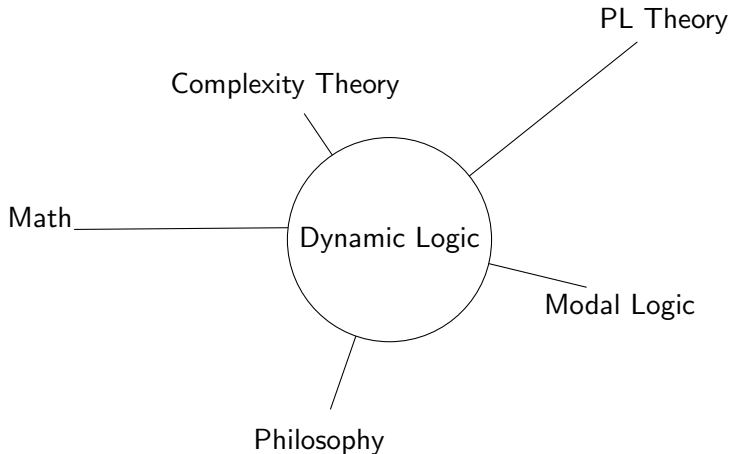


Table of Contents

- 1 Syntax and Semantics
- 2 Deterministic PDL
- 3 Proving Behavior in DPDL
- 4 Hoare Logic
- 5 Other Cool Stuff





IMPERATIVE CODE AHEAD



IMPERATIVE CODE AHEAD
(also math)

Section 1

Syntax and Semantics

Some philosophy...

Question: What is programming?

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(One possible) answer:

- Programming is the art of communicating with computers

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(One possible) answer:

- Programming is the art of communicating with computers
- We communicate with computers using otherwise-meaningless strings of symbols

Some philosophy...

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while true: print("AHHHH")
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fun fact 0 = 1
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```
/([a-z0-9\.-]+)@([\da-z\.-]+)\.([a-z\.]{2,6})/
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- Be sure our code will return the right result
- Know how long our code will take to run
- Be sure that we won't run into unforeseen bugs at runtime

Operational vs. Denotational

There are two main approaches to specifying programming language semantics: **operational semantics** and **denotational semantics**.

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In this lecture, I'll be focusing on the *denotational* approach.

Section 2

Deterministic PDL

DPDL

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- Interpretations of all the programs as *partial functions* on the state space
- A apparatus for formulating logical statements about the state space

The State Space

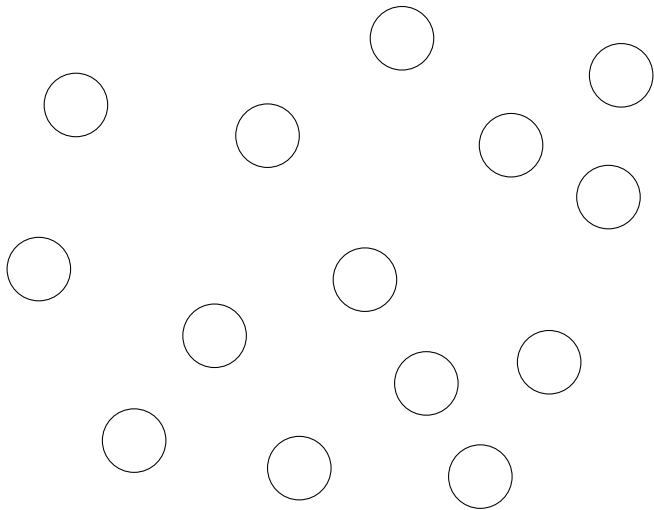
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X is often either finite or countably infinite, although in some applications we will want to have more states.

The State Space



The Programs

Let $\Pi = \{\pi_0, \pi_1, \dots\}$ be a set of “program names”.

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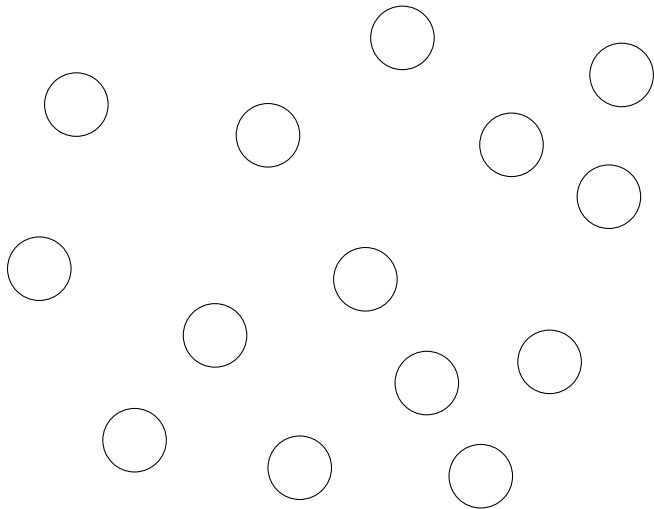
Let $\Pi = \{\pi_0, \pi_1, \dots\}$ be a set of “program names”.

Each program symbol $\pi \in \Pi$ *denotes* a partial function on our state space. We write this as:

$$\|\pi\| : X \rightarrow X$$

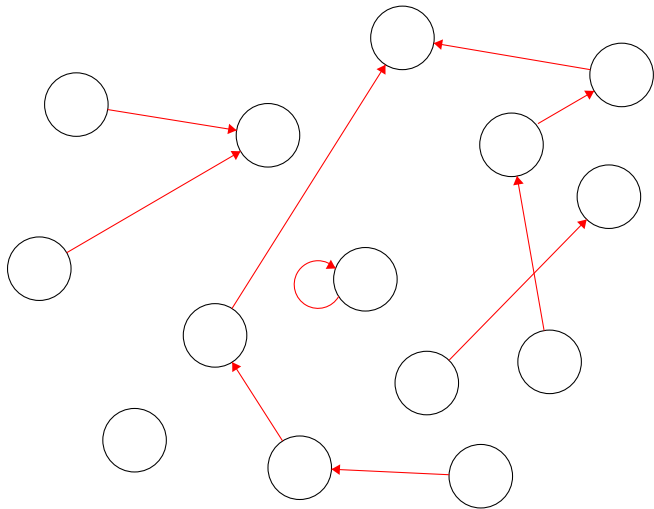
So, for each state $x \in X$, “executing π at x ” will either succeed (terminate) and result in a new state $\|\pi\|(x)$, or it will crash (encoded by $\|\pi\|(x)$ being undefined).

The Programs



The Programs

π_0



The Propositions

Let $\Phi = \{p_0, p_1, \dots\}$ be a countable set of “propositional variables”. These propositional variables denote logical statements we might want to make about a state x .

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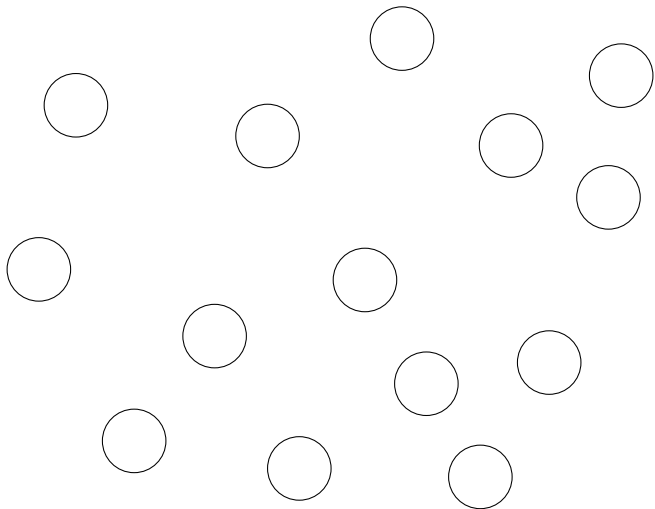
Let $\Phi = \{p_0, p_1, \dots\}$ be a countable set of “propositional variables”. These propositional variables denote logical statements we might want to make about a state x .

Each propositional variable $p \in \Phi$ *denotes* a subset of our state space. We write this as:

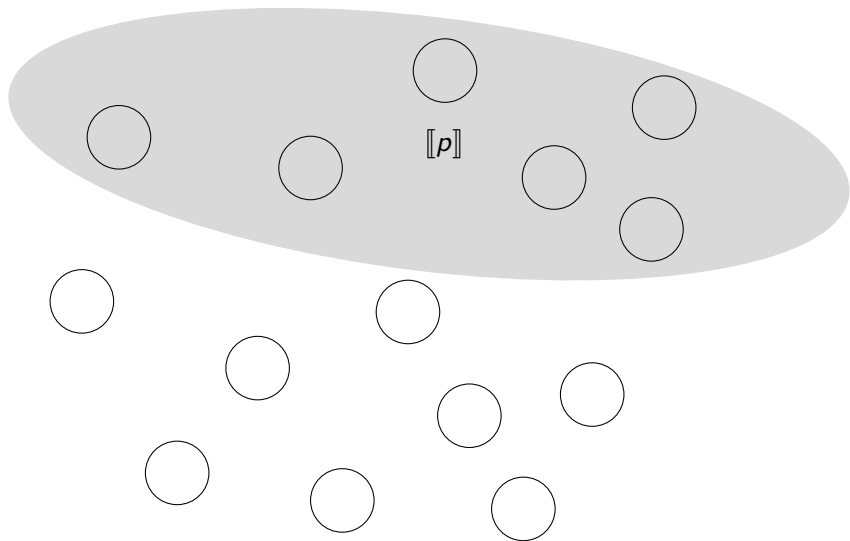
$$\llbracket p \rrbracket \subseteq X$$

Think of $\llbracket p \rrbracket$ as the set of states where p is true.

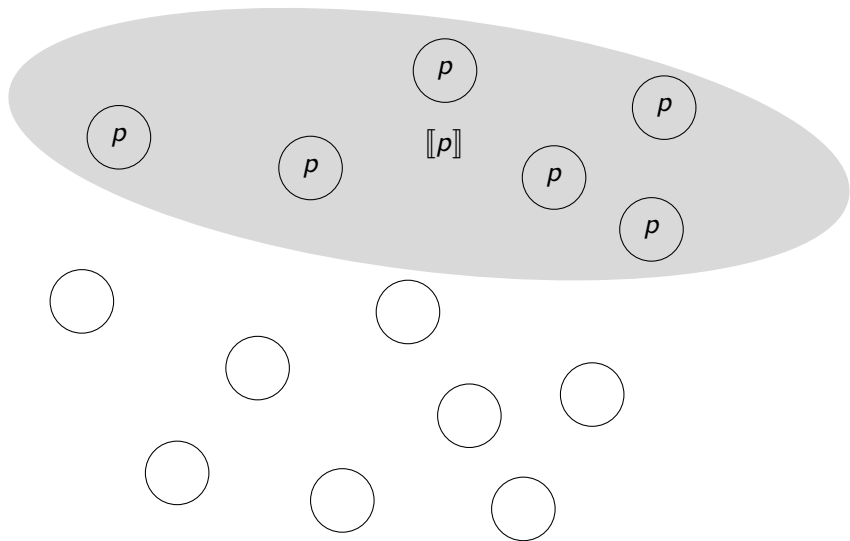
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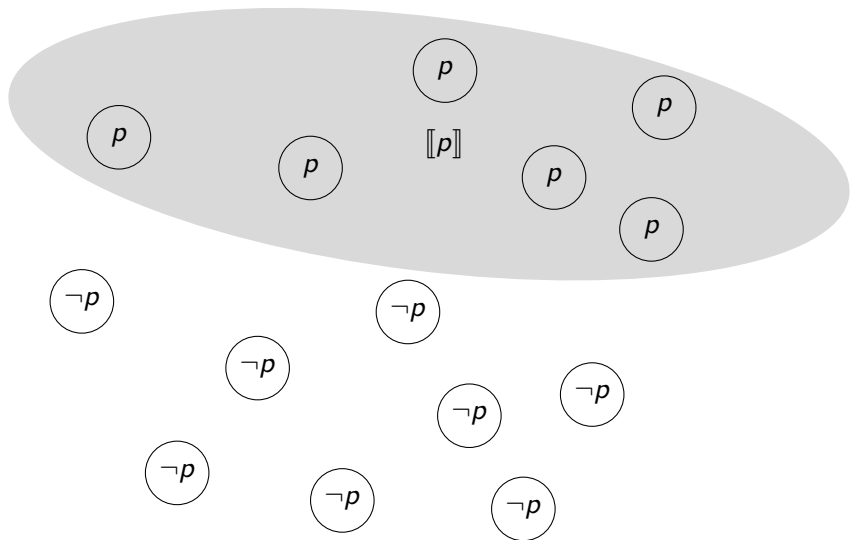
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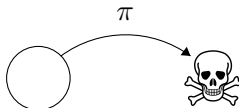
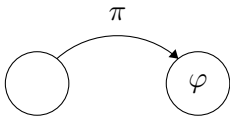
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The formula $\langle \pi \rangle \varphi$, which is defined to be $\neg[\pi]\neg\varphi$, expresses the statement “ π terminates, and results in a φ state”.

Sanity Check: What does this formula say?

$$\varphi \rightarrow \langle \pi \rangle \psi$$

(here, $p \rightarrow q$ is used as an abbreviation for $\neg p \vee q$).

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- A logical syntax to talk about state properties before and after executing a function

Section 3

Proving Behavior in DPDL

Based on how we set up the logic, the following rules are true **at every state of every model**, for any programs π, π_1, π_2 and any formulas φ, ψ, θ :

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$$\frac{(\varphi \wedge \psi) \rightarrow [\pi]\psi}{\psi \rightarrow [\mathbf{while} \ \varphi \ \mathbf{do} \ \pi](\neg\varphi \wedge \psi)}$$

Section 4

Hoare Logic

From PDL to Hoare Logic

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- $\{n \geq 0\} i := n \{i \geq 0\}$
- $\{a = b^i\} a := a * b \{a = b^{i+1}\}$

Here are our rules from earlier, in the Hoare notation:

$$\frac{\{\varphi\} \pi_1 \{\psi\} \quad \{\psi\} \pi_2 \{\theta\}}{\{\varphi\} \pi_1; \pi_2 \{\theta\}}$$

$$\frac{\{\varphi\} \pi_1 \{\psi\} \quad \{\neg\varphi\} \pi_2 \{\psi\}}{\{\text{if } \varphi \text{ then } \pi_1 \text{ else } \pi_2\} \{\psi\}}$$

$$\frac{\{\varphi \wedge \psi\} \pi \{\psi\}}{\{\psi\} \text{while } \varphi \text{ do } \pi \{\neg\varphi \wedge \psi\}}$$

A 122-style example

```
i:=n;  
res:=1;  
(while (i>0)  
do  
  
    res := res * b;  
    i := i-1  
  
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);  
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$\{n \geq 0\}$

$i := n;$

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$\{i \geq 0 \wedge res * b^i = b^n\}$

(while ($i > 0$))

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$res := res * b;$

$i := i - 1$

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);

$\{\neg(i > 0) \wedge i \geq 0 \wedge res * b^i = b^n\}$

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- Nondeterministic program semantics (replace the partial functions with binary relations)
- Heap Allocation
- Concurrency
- Cost Semantics
- More complex mathematics to make the modal logic more powerful (topological structure, structure-preserving maps and category theory, etc.)

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- So stay tuned...

Thank you!